# SIGNAL ENCODING TECHNIQUES

Data transmission Lecture#7 Dr. Emad Tammam

# Contents

- Encoding techniques
- Digital Data, Digital Signals
- Digital Data, Analog Signals

# Why?!!

• To optimize the use of transmission media, i.e., conserve BW or minimize the errors.

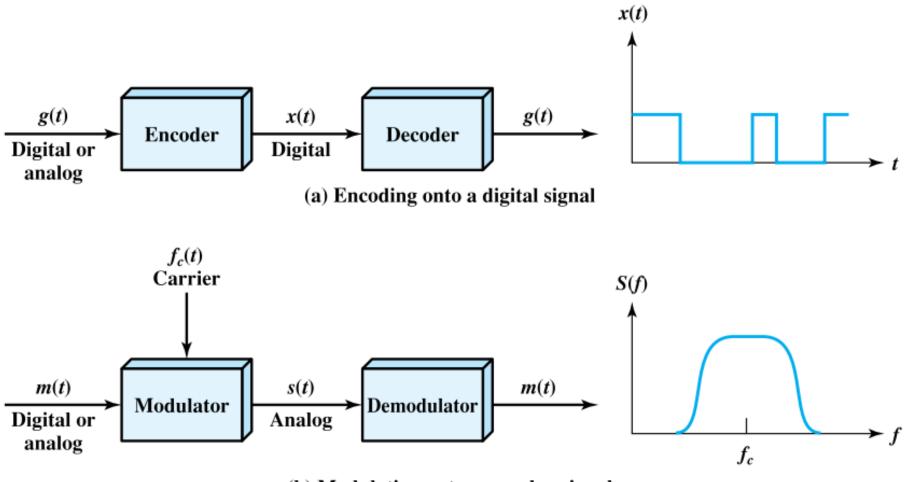
# **Choice of encoding techniques**

 Depends on the specific requirements to be met and the media and communications facilities available.

# Forms of encoding techniques

- Digital data, digital signals (line coding)
- Digital data, analog signal (ASK, FSK, PSK, ...)
- Analog data, digital signals (PCM, DM)
- Analog data, analog signals (AM, FM, PM)

# **Digital and analog signaling**



(b) Modulation onto an analog signal

### **Reasons for choosing a particular technique**

- Digital data, digital signal
  Equipment for encoding digital data into a digital signal is less complex and less expensive.
- Analog data, digital signal
  Permits the use of modern digital transmission and switching equipment.
- Digital data, analog signal

Some transmission media, such as optical fiber and unguided media, will only propagate analog signals.

• Analog data, analog signal Frequency division multiplexing.

# **Data element and signal element**

Term	Units	Definition
Data element	Bits	A single binary one or zero
Data rate	Bits per second (bps)	The rate at which data elements are transmitted
Signal element	Digital: a voltage pulse of constant amplitude	That part of a signal that occupies the shortest interval of a signaling code
	Analog: a pulse of constant frequency, phase, and amplitude	
Signaling rate or modulation rate	Signal elements per second (baud)	The rate at which signal elements are transmitted

# **Unipolar and polar signaling**

• Unipolar: If the signal elements all have the same algebraic sign, i.e., all positive or negative.

 Polar signaling, if one logic state is represented by a positive voltage level, and the other by a negative voltage level.

### **Tasks of receiver**

• First, to know the timing of each bit.

• Second, to determine whether the signal level for each bit position is high or low.

# Quality of receiving data

- For successful receiving, we are meant about:
- 1- SNR: increase in SNR decreases the bit error rate.
- 2- Data rate: increase in data rate increases the BER
- 3- BW: Increase in BW increases the data rate.
- Another factor that affects the transmission process is the encoding.
- Encoding: is the mapping of the data bits to signal element.

### **Encoding formats**

#### Nonreturn to Zero-Level (NRZ-L)

- 0 = high level
- 1 = low level

#### Nonreturn to Zero Inverted (NRZI)

- 0 = no transition at beginning of interval (one bit time)
- 1 = transition at beginning of interval

#### Bipolar-AMI

- 0 = no line signal
- 1 = positive or negative level, alternating for successive ones

#### Pseudoternary

- 0 = positive or negative level, alternating for successive zeros
- 1 = no line signal

#### Manchester

- 0 = transition from high to low in middle of interval
- 1 = transition from low to high in middle of interval

#### Differential Manchester

Always a transition in middle of interval

- 0 = transition at beginning of interval
- 1 = no transition at beginning of interval

#### B8ZS

Same as bipolar AMI, except that any string of eight zeros is replaced by a string with two code violations

#### HDB3

Same as bipolar AMI, except that any string of four zeros is replaced by a string with one code violation

#### Encoding formats, cont.

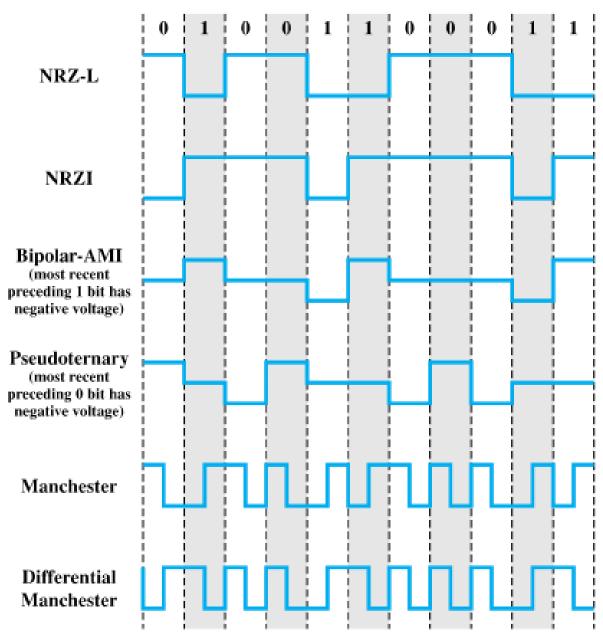


Figure 5.2 Digital Signal Encoding Formats

### Signal spectrum

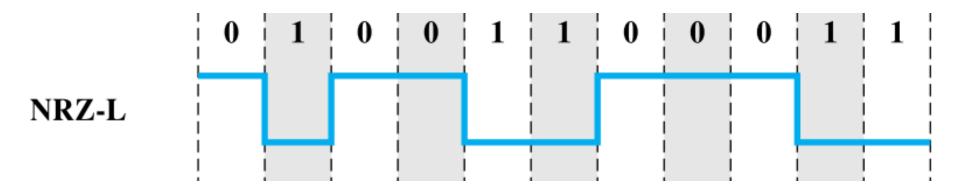
- Important aspects:
- Lack of high frequency components for low BW.
- No DC component make the ac coupling through transformers is possible. electrical isolation reduces the interference.
- Characteristics of the channel is worse near the edge, then, it is important to concentrate the power in the middle of the trans. BW.
- Codes are designed with the aim of shaping the spectrum of the signal.

# To evaluate the coding techniques

- Clocking:
- The synchronization can be achieved using suitable encoding.
- Error detection:
- Make use of the encoding scheme.
- Immunity to interference and noise :
- Certain codes exhibit superior performance in the presence of noise.
- Cost and complexity:
- Some codes require a signaling rate that is greater than the actual data rate, increasing the cost and complexity.

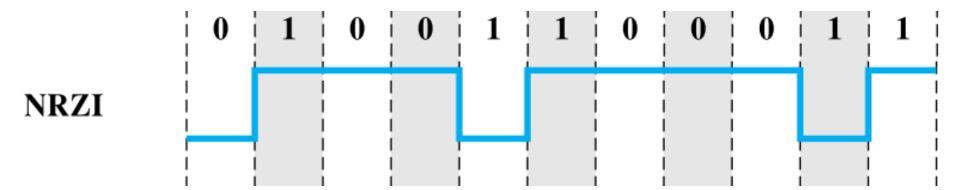
### Nonreturn to Zero (NRZ)

- NRZL(Nonreturn to Zero-Level)
- NRZ makes efficient use of the BW. BW is between dc and half the bit rate.
- For simplicity is used in digital magnetic recording.



# NRZI

- NRZI (Nonreturn to Zero, invert on ones)
- NRZI: an example of differential encoding
- In diff. encoding: represented in terms of the changes between successive signal elements rather than the signal elements themselves.



# **Benefits of diff. encoding**

 More reliable to detect a transition in the presence of noise than to compare a value to a threshold.

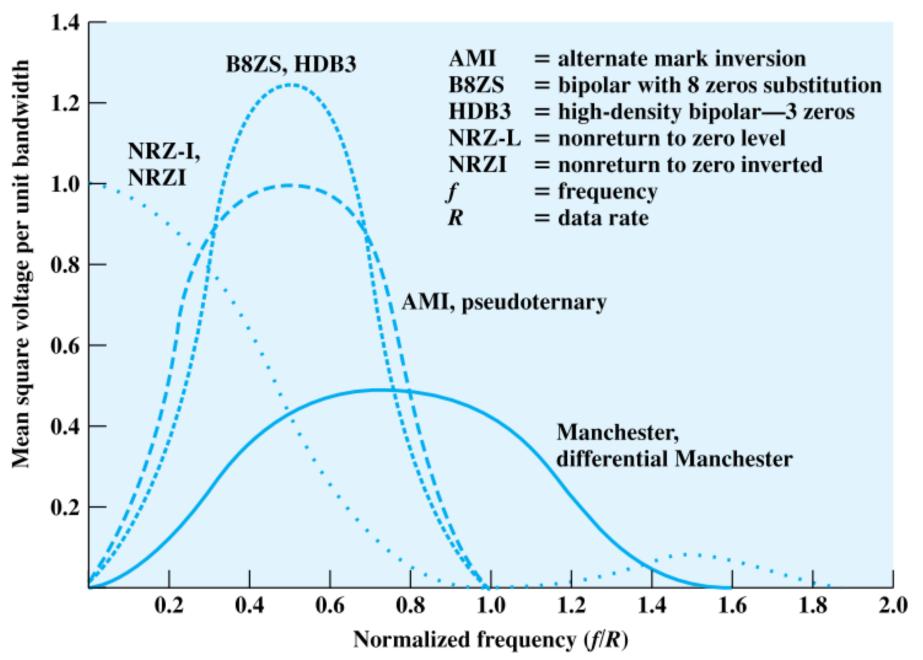
- It is easy to lose the sense of the polarity of the signal without problems.
- Ex. Of twisted-pair polarity and comparison with NRZL.

# Limitations of NRZ

- Presence of dc component.
- Lack of synchronization in case of long strings of 1s or 0s.

any drift between the clocks of transmitter and receiver will result in loss of synchronization between the two.

#### **BW comparison of different encoding techniques**



# **Multilevel Binary**

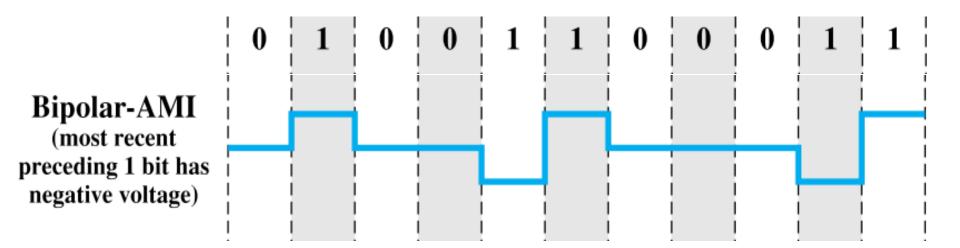
• Use more than two signal levels.

no line signal and a positive or negative pulse.

- Bipolar-AMI (alternate mark inversion) and pseudoternary.
- Overcome the problems of NRZ codes.

# **Bipolar-AMI**

 A binary 0 is represented by no line signal, and a binary 1 is represented by a positive or negative pulse. The binary 1 pulses must alternate in polarity.

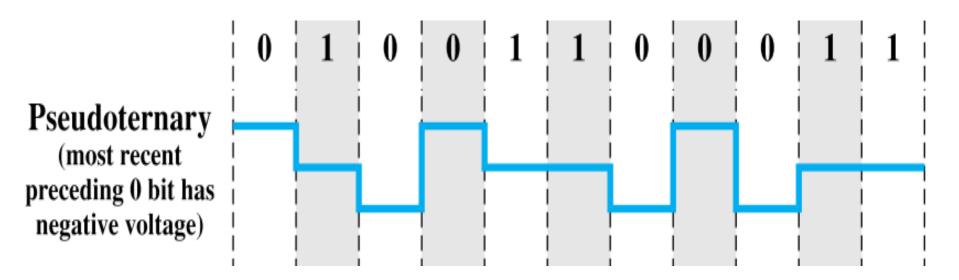


# **Advantages of bipolar-AMI**

- No dc components.
- No loss of synchronization in case of long 1s, but long 0s is problematic.
- Lower BW than NRZ.
- Pulse alternation give good mean for error detection.

# Pseudoternary

- Binary 1 is represented by the absence of a line signal, and the binary 0 by alternating positive and negative pulses.
- Problems of long strings of 1s in this case or 0s in the case of AMI can be solved by inserting additional bits for synch as in ISDN.



### **Disadvantages of multilevels encoding**

- Multilevels in not efficient as the NRZ because
- i.e., 3levels...and each level represents only 1 bit
- More power than the two levels system.
- More BER than NRZ at the same SNR.

### **BER for encoding schemes**

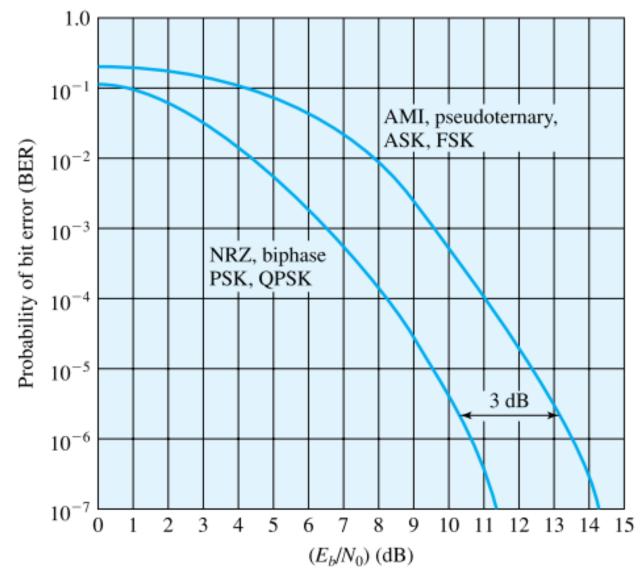
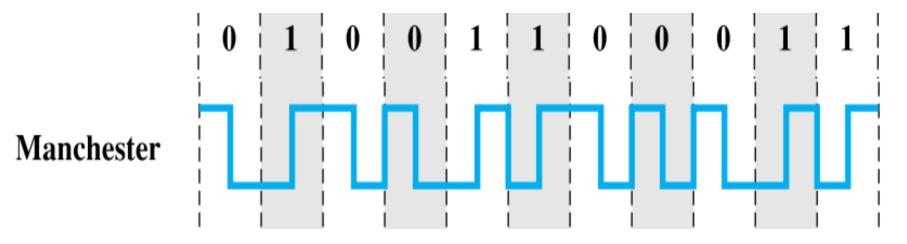


Figure 5.4 Theoretical Bit Error Rate for Various Encoding Schemes

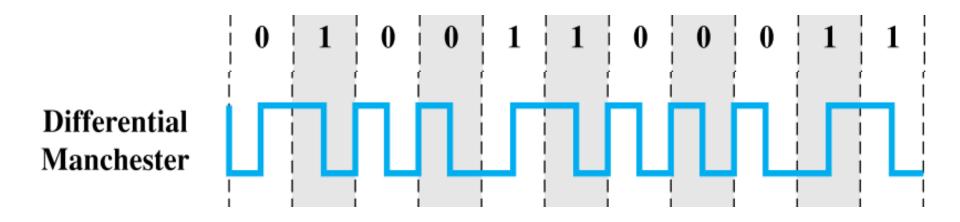
# Manchester

- It is a biphase encoding.
- Low-to-high transition represents a 1, and a high-tolow transition represents a 0.
- A transition at the middle of each bit period which serves as a clocking.
- Has been specified for the (Ethernet) standard for baseband coaxial cable and twisted-pair bus LANs.



### **Differential Manchester**

- 0 is represented by the presence of a transition at the beginning of a bit period, and 1 is represented by the absence of a transition at the beginning of a bit period.
- Midbit transition is used only to provide clocking.
- Has been specified for the IEEE 802.5 token ring LAN, using shielded twisted-pair.



# Biphase adv. and disadv.

#### Advantages:

- Synchronization: using transitions (self-clocking code).
- No dc component
- Error detection: The absence of an expected transition can be used to detect errors.

#### • **Disadvantages:**

- Maximum modulation rate is twice that for NRZ; the bandwidth required is correspondingly greater.

#### **Modulation Rate**

• The modulation rate is the rate at which signal elements are generated.

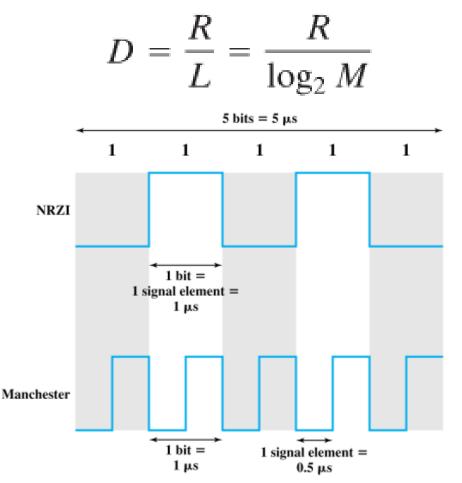


Figure 5.5 A Stream of Binary Ones at 1 Mbps

# Scrambling Techniques

- Sequences that would result in a constant voltage level on the line are replaced by filling sequences that will provide sufficient transitions for the receiver's clock to maintain synchronization.
- The filling sequence must be recognized by the receiver and replaced with the original data sequence.

### **Goals of scrambling**

- No dc component
- □ No long sequences of zero-level line signals
- □ No reduction in data rate
- Error-detection capability

# **Bipolar with 8-zeros substitution (B8ZS)**

- Commonly used in North America.
- Based on a bipolar-AMI.

 If an octet of all zeros occurs and the last voltage pulse preceding this octet was positive, then the eight zeros of the octet are encoded as 000+-0-+

• If an octet of all zeros occurs and the last voltage pulse preceding this octet was negative, then the eight zeros of the octet are encoded as 000-+0+-

## High-density bipolar-3 zeros (HDB3)

- Used in Europe and Japan.
- Based on the use of AMI.
- It replaces strings of four zeros with sequences containing one or two pulses.

	Number of Bipolar Pulses (ones) since Last Substitution	
Polarity of Preceding Pulse	Odd	Even
_	000-	+ 00 +
+	0 0 0 +	- 0 0 -

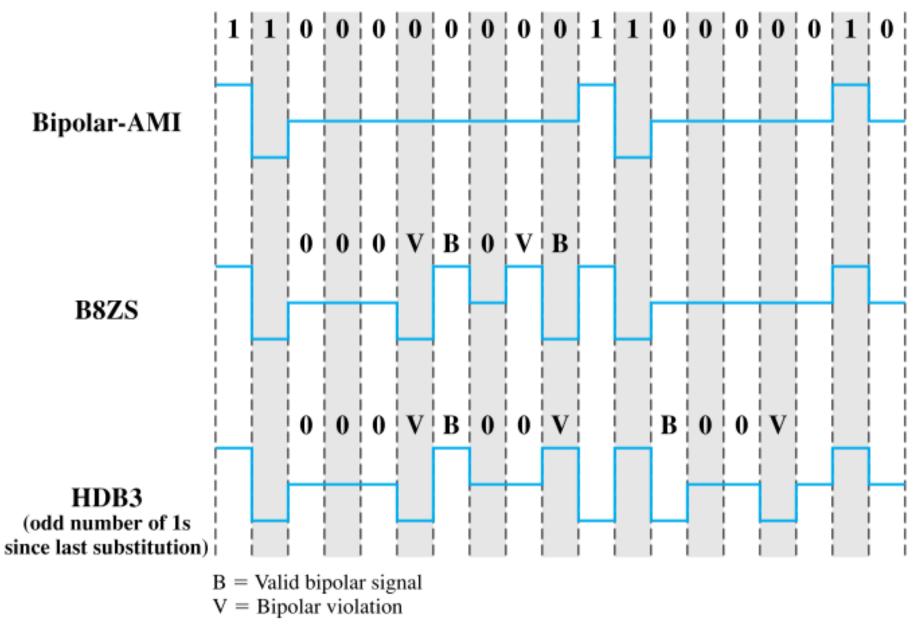


Figure 5.6 Encoding Rules for B8ZS and HDB3

### **Advantages of B8ZS and HDB3**

- Neither has a dc component.
- Most of the energy is concentrated in a sharp spectrum around a frequency equal to one-half the data rate.
- Well suited to high data rate transmission.

### Digital data, analog signals

- Used for transmitting digital data through the public telephone network.
  - Amplitude shift keying (ASK),
  - Frequency shift keying (FSK),
  - Phase shift keying (PSK).
- The resulting signal occupies a bandwidth centered on the carrier frequency.

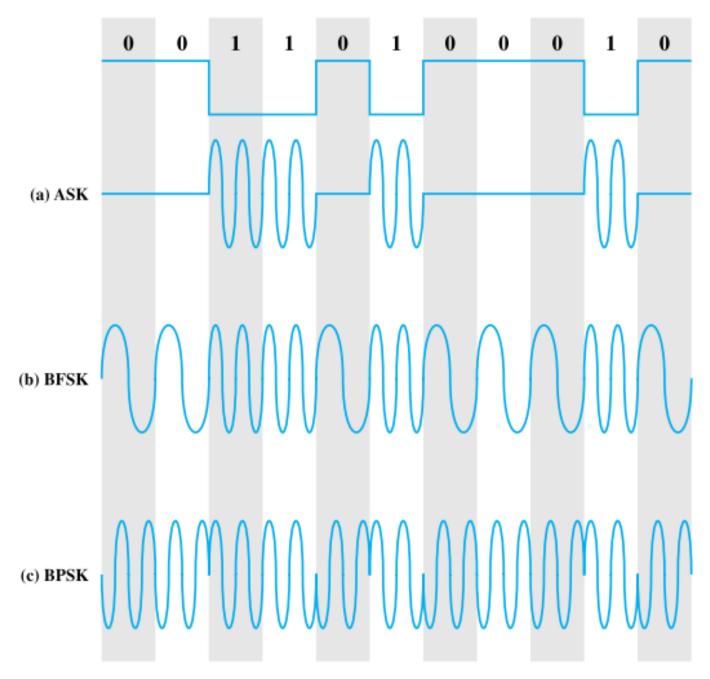


Figure 5.7 Modulation of Analog Signals for Digital Data

### ASK

- Two binary values are represented by two different amplitudes.
- ASK is susceptible to sudden gain changes.
- Is a rather inefficient modulation technique.
- Is used to transmit digital data over optical fiber.

**ASK** 
$$s(t) = \begin{cases} A \cos(2\pi f_c t) & \text{binary } 1 \\ 0 & \text{binary } 0 \end{cases}$$

FSK

- The most common form of FSK is binary FSK (BFSK).
- In BFSK, the two binary values are represented by two different frequencies near the carrier frequency.

**BFSK** 
$$s(t) = \begin{cases} A \cos(2\pi f_1 t) & \text{binary 1} \\ A \cos(2\pi f_2 t) & \text{binary 0} \end{cases}$$

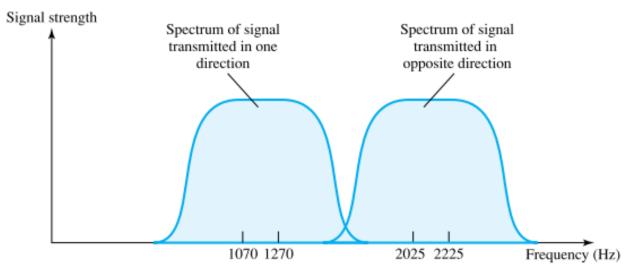


Figure 5.8 Full-Duplex FSK Transmission on a Voice-Grade Line

### FSK, cont.

- BFSK is less susceptible to error than ASK.
- Used for high-frequency (3 to 30 MHz).
- More bandwidth efficient is the multiple FSK (MFSK).
- More than two frequencies can be used (Multiple FSK). **MFSK**  $s_i(t) = A \cos 2\pi f_i t$ ,  $1 \le i \le M$

$$f_i = f_c + (2i - 1 - M)f_d$$

- $f_c$  = the carrier frequency
- $f_d$  = the difference frequency
- M = number of different signal elements =  $2^L$
- L = number of bits per signal element

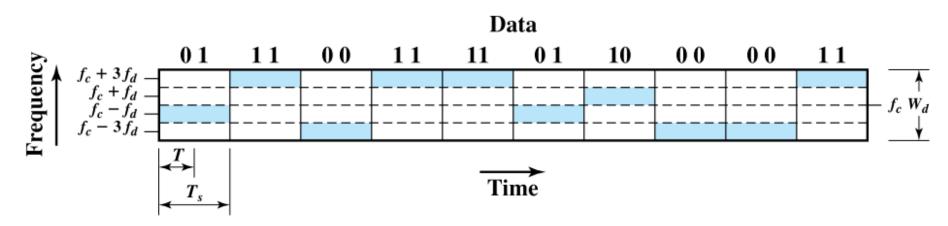
### MFSK

• Each output signal element is held for a period Ts=LT of seconds.

• Total BW is  $2Mf_d = M/Ts$ Where  $2f_d = 1/Ts$ 

#### Example

**EXAMPLE 5.2** Figure 5.9 shows an example of MFSK with M = 4. An input bit stream of 20 bits is encoded 2 bits at a time, with each of the four possible 2-bit combinations transmitted as a different frequency. The display in the figure shows the frequency transmitted (y-axis) as a function of time (x-axis). Each column represents a time unit  $T_s$  in which a single 2-bit signal element is transmitted. The shaded rectangle in the column indicates the frequency transmitted during that time unit.



**Figure 5.9** MFSK Frequency Use (M = 4)

### Phase Shift Keying (PSK)

• The carrier signal is shifted to represent data.

• <u>Two-Level PSK:</u>

**BPSK** 
$$s(t) = \begin{cases} A\cos(2\pi f_c t) \\ A\cos(2\pi f_c t + \pi) \end{cases} = \begin{cases} A\cos(2\pi f_c t) & \text{binary } 1 \\ -A\cos(2\pi f_c t) & \text{binary } 0 \end{cases}$$

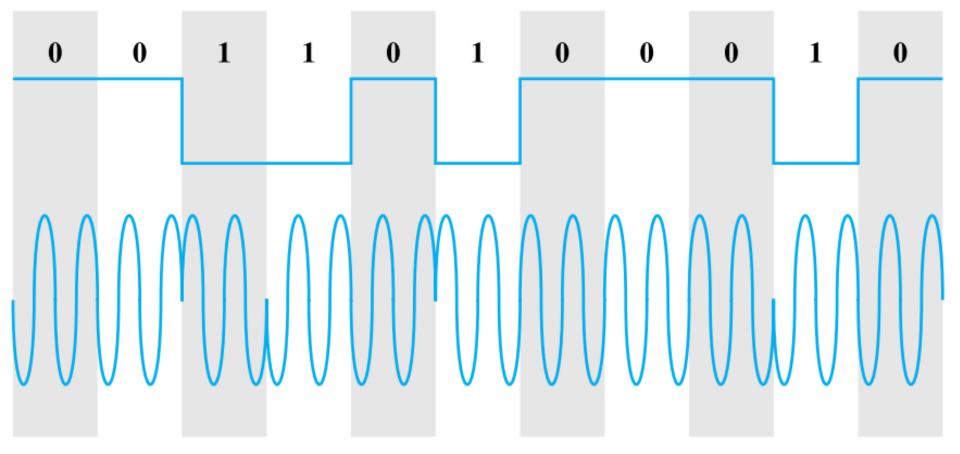
• We can define the transmitted signal as

**BPSK** 
$$s_d(t) = A d(t) \cos(2\pi f_c t)$$

# **Differential PSK (DPSK)**

- A binary 0 is represented by sending a signal burst of the same phase as the previous signal burst sent.
- A binary 1 is represented by sending a signal burst of opposite phase to the preceding one.

### Differential PSK (DPSK), cont.

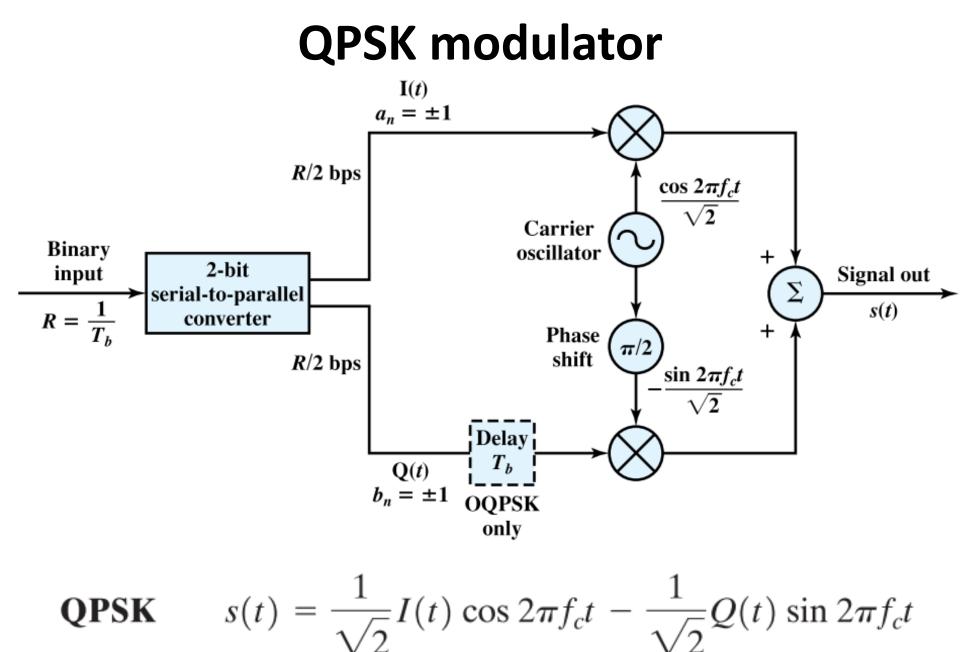


 DPSK avoids the requirement for an accurate local oscillator phase at the receiver that is matched with the transmitter.

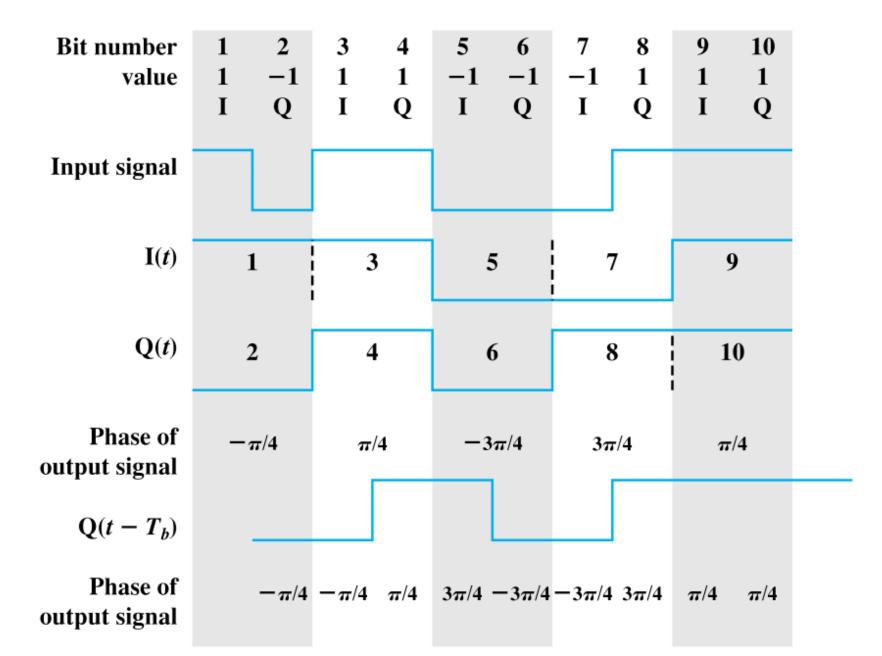
#### **Four-Level PSK**

- known as quadrature phase shift keying (QPSK).
- Uses phase shifts separated by multiples of  $\pi/2$ .
- More efficient use of bandwidth can be achieved.

$$\mathbf{QPSK} \quad s(t) = \begin{cases} A \cos\left(2\pi f_c t + \frac{\pi}{4}\right) & 11 \\ A \cos\left(2\pi f_c t + \frac{3\pi}{4}\right) & 01 \\ A \cos\left(2\pi f_c t - \frac{3\pi}{4}\right) & 00 \\ A \cos\left(2\pi f_c t - \frac{\pi}{4}\right) & 10 \end{cases}$$



#### **Example of QPSK and OQPSK**



### Advantage of OQPSK over QPSK

- Spectral characteristics and bit error performance are the same for the two.
- In OQPSK, only one of two bits in the pair can change sign at any time and thus the phase change in the combined signal never exceeds 90°
- Large phase shifts at high transition rates difficult to perform because physical limitations on phase modulators.
- It is easier to control the BW spreading if the phase changes are smaller.

### **Multilevel PSK**

- It is possible to transmit number of bits at a time using different phases.
- Each angle can have more than one amplitude.
- For example, a standard 9600 bps modem uses 12 phase angles, four of which have two amplitude values, for a total of 16 different signal elements.

### Performance

- **<u>Bandwidth</u> ASK**  $B_T = (1 + r)R$  **MPSK**  $B_T = \left(\frac{1 + r}{L}\right)R = \left(\frac{1 + r}{\log_2 M}\right)R$ **MFSK**  $B_T = \left(\frac{(1 + r)M}{\log_2 M}\right)R$
- Where R is the bit rate and r is related to the technique by which the signal is filtered to establish a bandwidth for transmission 0 < r < 1
- L is the number of bits encoded per signal element and M is the number of different signal elements.

## Bandwidth Efficiency $(R/B_T)$

	r = 0	r = 0.5	<i>r</i> = 1
ASK	1.0	0.67	0.5
FSK	0.5	0.33	0.25
Multilevel FSK			
M = 4, L = 2	0.5	0.33	0.25
M = 8, L = 3	0.375	0.25	0.1875
M = 16, L = 4	0.25	0.167	0.125
M = 32, L = 5	0.156	0.104	0.078
PSK	1.0	0.67	0.5
Multilevel PSK			
M = 4, L = 2	2.00	1.33	1.00
M = 8, L = 3	3.00	2.00	1.50
M = 16, L = 4	4.00	2.67	2.00
M = 32, L = 5	5.00	3.33	2.50

#### **Quadrature Amplitude Modulation**

- Is used in the asymmetric digital subscriber line (ADSL).
- Is a combination of ASK and PSK.
- Uses two copies of the carrier frequency, one shifted by 90° with respect to the other.
- For QAM, each carrier is ASK modulated.
- The two independent signals are simultaneously transmitted over the same medium.

**QAM** 
$$s(t) = d_1(t)\cos 2\pi f_c t + d_2(t)\sin 2\pi f_c t$$

#### **QAM modulator**

